

Solutions to Boltzmann equation

Global equilibrium ($\frac{\delta f_{0q}}{\delta t} = 0$)

We found that in the absence of external forces

Maxwell-Boltzmann distribution

$$f(t, \vec{r}, \vec{p}) = f_{0q}(\vec{p}) = n \left(\frac{2\pi m k_B T}{m k_B T} \right)^{3/2} e^{-\frac{(\vec{p} - m\vec{v}_0)^2}{2m k_B T}}$$

is a stationary solution of the Boltzmann equation, described by

n number density

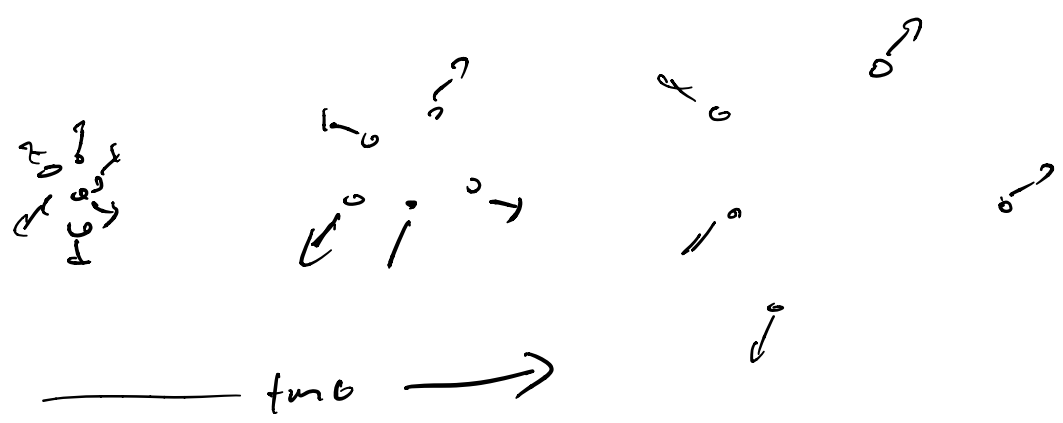
\vec{v}_0 velocity

T temperature

Since this distribution describes a thermodynamic equilibrium state, its entropy is maximal and one could expect any system to approach such a state on large time scales as $\frac{dS}{dt} \geq 0$ in the Boltzmann equation.

However there are counter examples and
no theorem does not guarantee convergence
to an equilibrium state at late times

e.g. If phase space is unbounded the
system may continue to expand



Systems confined to a finite
volume may exhibit periodic
behavior (e.g. Lorenz attractor)

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Evidently global equilibrium solutions are relatively easy to find but often not particularly interesting, and we will now try to construct approximate solutions exploiting once again the fact that in many systems there can be a separation of scales

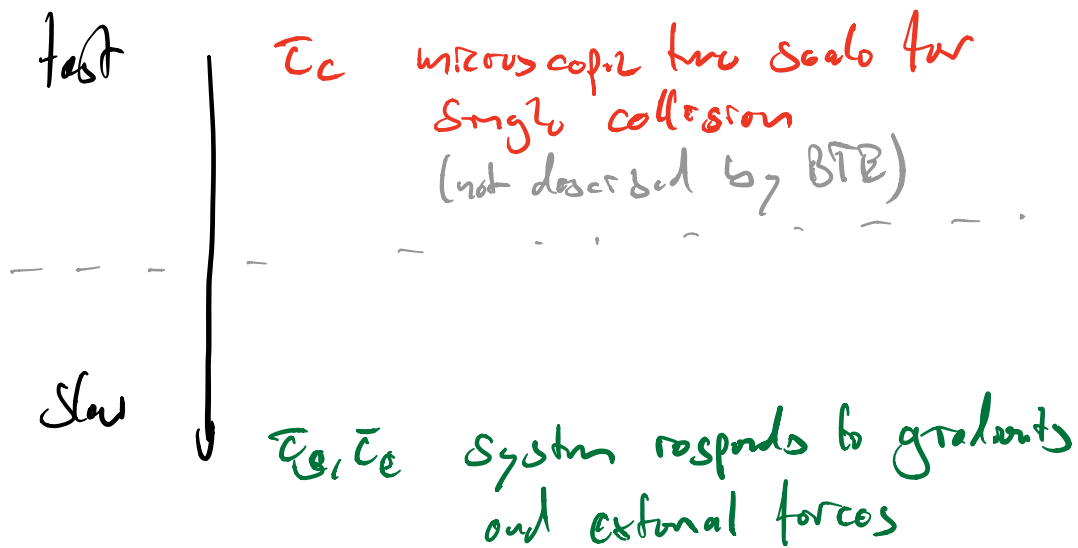
Local equilibrium solutions: $(f^{(0)}(t, \vec{r}, \vec{p}))$

Strictly speaking are not solutions of BTE, but only defined by the requirement that

$$C[f^{(0)}](t, \vec{r}, \vec{p}) = 0$$

Nevertheless conceptually important if we assume a separation of scales

Downing - the BTE no had already encounters
different scales



Downing $\tau_S \sim \left(\vec{v} \frac{\partial f}{\partial t} \right)^{-1} \sim \frac{L}{v_{th}}$ with

a macroscopic length scale L wo

Should also compare τ_c to the
typical time scale between collision
events

mean free time:

$$\tau_{mfp} \sim \left(\frac{\left(\frac{d\Gamma}{dt} \right)_{\text{coll}}}{f} \right)^{-1} \sim \frac{1}{n \sigma_{\text{tot}} v_{\text{th}}}$$

Now using $\tau_{mfp} = \frac{l_{mfp}}{v_{\text{th}}}$ we get

mean free path: $l_{mfp} \sim \frac{1}{n \sigma_{\text{tot}}}$

Such that the ratio of the scales

$$\frac{\tau_{mfp}}{\tau_S} \sim \frac{l_{mfp}}{L} \equiv \kappa_n$$

Now it is important to remember that the derivation of the Boltzmann equation only requires

collision
time

$$\bar{\tau}_c \ll \tau_{\text{mp}}$$

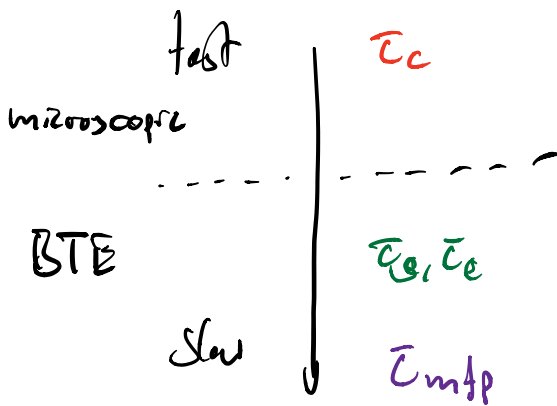
typical time
between collisions

but so far we did not make
any assumptions on the ordering
of the scales $\tau_{\text{mp}}, \tau_s, \tau_c$

Now if we assume a separation of
scales between τ_{mp} and τ_s, τ_c
we can distinguish to qualitatively
different regimes, where we can
systematically derive solutions to BTE

$$k_{\eta} \gg 1$$

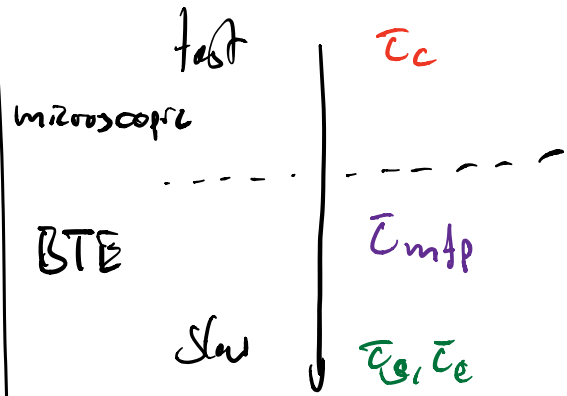
$$\tau_{\text{mfp}} \gg \bar{\tau}_s, \bar{\tau}_e$$



System is essentially free streaming up to corrections due to rare collision events

$$k_{\eta} \ll 1$$

$$\tau_{\text{mfp}} \ll \bar{\tau}_s, \bar{\tau}_e$$



Several collisions occur during the response to gradients and external forces

When $|k_{on} \ll 1|$ collisions are very frequent
on macroscopic time scales τ_s, τ_e

Since collisions are local events that
lead to equilibration of the momentum
distribution, we can assume that
locally the system relaxes to
an equilibrium momentum distribution
long before it eventually may or
may not reach global equilibrium.

Becomes useful to characterize
intermediate states by

local equilibrium solutions: $(C[f^{(0)}] = 0)$

$$f^{(0)}(t, \vec{r}, \vec{p}) = n(t, \vec{r}) \left(\frac{2\pi\hbar^2}{m k_B T(t, \vec{r})} \right)^{3/2} e^{-\frac{(\vec{p} - m\vec{v}(t, \vec{r}))^2}{2m k_B T(t, \vec{r})}}$$

where $n(t, \vec{r})$, $T(t, \vec{r})$, $\vec{v}(t, \vec{r})$ are

locally defined at each point as

Speco in time

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Now if we consider the limit $Kn \ll 1$
 we can obtain approximate solutions
 to BTE by expanding around local
 equilibrium distribution

$$f(t, \vec{r}, \vec{p}) = \underbrace{f^{(0)}(t, \vec{r}, \vec{p})}_{\text{local equilibrium}} + \underbrace{f^{(1)}(t, \vec{r}, \vec{p})}_{\text{non-equilibrium corrections}} + \dots$$

where $f^{(1)}(t, \vec{r}, \vec{p})$ is a small correction
 with $|f^{(1)}(t, \vec{r}, \vec{p})| \sim O(Kn)$

Expanding in Kn , the dynamics of $f^{(1)}$
 will be governed by linearized BTE
 and there are different strategies to
 organize the expansion based on
 the power counting of various terms
 in BTE

We will discuss one particular expansion
 scheme which we will need to derive
 hydrodynamic from BTE

Hilbert Expansion:

Generally we find that Good on our ansatz

$$\frac{\partial f^{(0)}}{\partial t} + \frac{\partial f^{(1)}}{\partial t} + \vec{v} \vec{\partial}_r f^{(0)} + \vec{v} \vec{\partial}_r f^{(1)} + \vec{v} \vec{\partial}_p f^{(0)} + \vec{v} \vec{\partial}_p f^{(1)} = C[f^{(0)}, f^{(1)}]$$

where we can express the collision integral as

$$C[f^{(0)}, f^{(1)}] = C[f^{(0)}] + \delta C[f^{(0)}, f^{(1)}]$$

with

$$\delta C[f^{(0)}, f^{(1)}] = \sum_{p_2 p_3 p_4} \tilde{w}(p_1, p_2 \rightarrow p_3, p_4)$$

$$\left[f_3^{(0)} f_4^{(1)} + f_3^{(1)} f_4^{(0)} - f_1^{(0)} f_2^{(1)} - f_1^{(1)} f_2^{(0)} \right]$$

So if we power count the individual terms, we have

$$\begin{aligned}
 C[f^{(0)}] &\sim \frac{1}{\bar{c}_{\text{imp}}} f^{(0)} \\
 \delta C[f^{(0)}, f^{(1)}] &\sim \frac{1}{\bar{c}_{\text{imp}}} f^{(1)} \sim K_{\eta} \frac{1}{\bar{c}_{\text{imp}}} f^{(0)} \\
 \frac{\delta}{\delta t} f_0 &\sim \frac{1}{\bar{c}_S} f^{(0)} \sim K_{\eta} \frac{1}{\bar{c}_{\text{imp}}} f^{(0)} \\
 \vec{\nabla} \vec{\nabla}_r f_0 &\sim \frac{1}{\bar{c}_S} f^{(0)} \sim K_{\eta} \frac{1}{\bar{c}_{\text{imp}}} f^{(0)} \\
 \vec{\nabla} \vec{\nabla}_p f_0 &\sim \frac{1}{\bar{c}_S} f^{(0)} \sim K_{\eta} \frac{1}{\bar{c}_{\text{imp}}} f^{(0)}
 \end{aligned}$$

Since on large time scales ($\sim \bar{c}_S$) deviations from local equilibrium ($f^{(1)}$) occur in response to gradients and external forces, we can find a consistent truncation scheme

$$f^{(1)}(t, \vec{r}, \vec{p}) \sim K_{\eta} f^{(0)}(t, \vec{r}, \vec{p})$$

$$O(k_n^0): \quad \boxed{C[f^{(0)}] = 0}$$

$\Rightarrow f^{(0)}$ is local equilibrium distribution

$$O(k_n^1): \quad \boxed{\mathcal{S}C[f^{(0)}, f^{(1)}] = \left(\frac{\partial}{\partial t} + \vec{v} \cdot \vec{\nabla}_r + \vec{F} \cdot \vec{\nabla}_p \right) f^{(0)}}$$

\Rightarrow solution for $f^{(1)}$ requires inversion of collision operator $\mathcal{S}C[f^{(0)}, f^{(1)}]$

Hilbert expansion can be developed to higher orders, which is e.g. required for the calculation of higher order transport coefficients

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Discussion shows that solutions to BTE are hard to find even in the limit $\kappa_{coll} \ll \kappa_{tr}$ where deviations from local equilibrium are small, as inverse of $SC[f^{(0)}, f^{(1)}]$ is highly non-trivial

In practice one often employs simplified versions of the collision kernel, with the simplest physical one given by

Relaxation time approximation (RTA)

Expect that small deviations from equilibrium will relax exponentially towards equilibrium on a time scale

relaxation time: $\tau_R(T(\vec{r}), n(\vec{r}), \vec{p})$

suggests to approximate

$$SC_{RTA}[f^{(0)}, f^{(1)}] = - \frac{f^{(1)}(t, \vec{r}, \vec{p})}{\tau_R(T(\vec{r}), n(\vec{r}), \vec{p})}$$

Even beyond the linearized description
 RTA is frequently employed as approximation
 of BTE. In this case one approximates
 the full collision integral as

$$C[f] \approx - \frac{f - f^{(0)}}{\tau_R}$$

where in this case the parameters
 $\vec{v}(t, \vec{r})$, $T(t, \vec{r})$, $n(t, \vec{r})$ characterizing
 the local equilibrium state $f^{(0)}$ have
 to be determined from the single
 particle distribution f , such that
 particle number, momentum and energy
 are conserved by $C_{RTA}[f]$

eg. \bar{c}_R independent of \vec{p}

$$n[\vec{f}](t, \vec{r}) = \int \frac{d^3 p}{(2\pi\hbar)^3} f(t, \vec{r}, \vec{p}) \rightarrow n(t, \vec{r})$$

$$\vec{P}[\vec{f}](t, \vec{r}) = \int \frac{d^3 p}{(2\pi\hbar)^3} \vec{p} f(t, \vec{r}, \vec{p}) \rightarrow \vec{V}(t, \vec{r})$$

$$e_{\text{kin}}[\vec{f}](t, \vec{r}) = \int \frac{d^3 p}{(2\pi\hbar)^3} \frac{\vec{p}^2}{2m} f(t, \vec{r}, \vec{p}) \rightarrow T(t, \vec{r})$$

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Now that we have a systematic expansion for U_{CC1} along with sufficiently simple approximations for $\delta C[\vec{f}^{(0)}, \vec{f}^{(1)}]$, will connect to macroscopic description of nonequilibrium systems and discuss calculation of transport coefficients